Lecture 7 Trajectory analysis

Trajectory inference (TI) for scRNA-seq

- Understand the cell fate decisions in biological processes, such as differentiation, immune response, or cancer expansion with scRNA-seq data
- Infer or assume a type of underlying trajectory structure



- Computationally project and order the cells along the trajectory
- The orders of the cells are also called the pseudotimes



• There already exists more than 70 TI methods (For a comprehensive benchmarking, see Saelens W. et. al., *Nat. Biotech.* **37**, 547–554(2019))

Slingshot (Street et. al., BMC Genomics, 2018)

• Idea: build a connection graph for the clusters



- Main steps:
 - Dimension reduction and clustering
 - Treat clusters as nodes in a graph and draw a minimum spanning tree (MST)
 - MST: spanning tree whose weights (sum of its edge weights) is the smallest among spanning trees
 - Greedy MST algorithm to find the solution
 - Tutorial: <u>https://algs4.cs.princeton.edu/43mst/</u>
 - Edge weight: distance between two clusters

$$d^2(\mathcal{C}_i,\mathcal{C}_j)\equiv (ar{X}_i-ar{X}_j)^T(S_i+S_j)^{-1}(ar{X}_i-ar{X}_j)$$



An edge-weighted graph and its MST

Slingshot (Street et. al., BMC Genomics, 2018)

- Main steps:
 - Estimate the lineage (trajectory) structure
 - Dimension reduction and clustering
 - Treat clusters as nodes in a graph and draw a minimum spanning tree (MST)
 - Undirected tree -> directed tree: user provided initial cluster
 - Perform constrained MST if users provide the leaf node
 - Drawback: what if the lineage structure is not a tree?
 - Estimate a cell pseudotime
 - For each lineage (path from initial node to a leaf node), fit a principal curve and project the cells onto the principal curve to determine the pseudotime



• Challenge: shared lineages should have overlapping principal curves and cells belonging to multiple lineages should have similar pseudotime estimates

Slingshot (Street et. al., BMC Genomics, 2018)

Principal curve (Hastie and ٠ Stuetzle, JASA 1989)





Generalization of getting first • (linear) PC

 $\mathbf{x}_i = \mathbf{f}(\lambda_i) + \mathbf{e}_i$



PAGA (Wolf et. al., Genome Biology, 2019)

- Construct KNN graph of the cells (use any reasonable method, can apply denoising first)
- Clustering and determine connectivity between clusters based on the KNN graph
 - ε_{ii}^{sym} : number of edges (outgoing and ingoing) between cluster *i* and *j*
 - Under the "null" where there is no connection between the two clusters $p_{\text{arbit}}(\varepsilon|e_i, e_j, n_i, n_j, n) \simeq \mathcal{N}(\varepsilon|\hat{\varepsilon}^{\text{sym}}(e_i, e_j, n_i, n_j, n), \hat{\sigma}^{\text{sym}}(e_i, e_j, n_i, n_j, n))$ with $\hat{\varepsilon}^{\text{sym}}(e_i, e_j, n_i, n_j, n) = \frac{e_i n_j + e_j n_i}{n-1},$ $\hat{\sigma}^{\text{sym}}(e_i, e_j, n_i, n_j, n) = \frac{e_i n_j (n-n_j-1) + e_j n_i (n-n_i-1)}{(n-1)^2}.$
 - n_i : number of nodes in cluster *i*, e_i : number of outgoing edges of cluster *i*
 - Cluster connectivity score:

$$c_{ij} = \begin{cases} \frac{\varepsilon_{ij}^{\text{sym}}}{\hat{\varepsilon}^{\text{sym}}(e_i, e_j, n_i, n_j, n)} & \text{if } \varepsilon_{ij}^{\text{sym}} < \hat{\varepsilon}^{\text{sym}}(e_i, e_j, n_i, n_j, n) \\ 1 & \text{else.} \end{cases}$$

• Thresholding cluster connectivity score to get the final trajectory structure



PAGA (Wolf et. al., Genome Biology, 2019)

- Pseudotime estimation for each cell (DPT)
 - Pseudotime defined as the distance of a continuous progression along a manifold
 - Based on a diffusion maps model on the cell-cell graph (like MAGIC, cell-cell transition matrix T)
 - Some highlights of the algorithm
 - Laplace transformation

$$\widetilde{L} = I - \widetilde{T}, \quad \widetilde{T} = D^{\frac{1}{2}}TD^{-\frac{1}{2}}$$

• Calculate diffusion pseudotime based on the eigenvectors and eigenvalues of L (or equivalently, T) n_{nodes}

$$\widetilde{\operatorname{dpt}}^{2}(\iota_{1},\iota_{2}) = \sum_{r=2}^{n_{\operatorname{nodes}}} \left(\frac{\lambda_{r}}{1-\lambda_{r}}\right)^{2} (\widetilde{v}_{r\iota_{1}} - \widetilde{v}_{r\iota_{2}})^{2}$$

 Making using of trajectory structure: assign ∞ to cell-cell distance for cells in disconnected clusters

$$\widetilde{\operatorname{dpt}}(\iota_1, \iota_2) = \sum_{r=n_{\text{comps}}+1}^{n_{\text{nodes}}} \left(\frac{\lambda_r}{1-\lambda_r}\right)^2 (\widetilde{v}_{r\iota_1} - \widetilde{v}_{r\iota_2})^2 + \sum_{r=1}^{n_{\text{comps}}} (\widetilde{v}_{r\iota_1} - \widetilde{v}_{r\iota_2})^2$$

VITAE (Du et. al., BioRXiv, 2023)

- Combine a graph-based method and direct modeling of the data using variational autoencoder
- Assume a complete graph $\mathcal{G} = (\mathcal{N}, \mathcal{E})$
 - $\mathcal{N}(\mathcal{G})$: a vertex denotes a distinct cell state / type
 - $\mathcal{E}(\mathcal{G})$: an edge denotes a possible transition between two cell states/types
- A cell position $\widetilde{w}_i \in [0, 1]^k$ on the graph



 $\tilde{\boldsymbol{w}}_{i} = \begin{cases} \boldsymbol{e}_{j} & \text{if cell } i \text{ is on vertex } j \in \{1, \cdots, k\} \\ w_{i}\boldsymbol{e}_{j_{1}} + (1 - w_{i})\boldsymbol{e}_{j_{2}} & \text{if cell } i \text{ is on the edge between vertices } j_{1} \text{ and } j_{2} \ (j_{1} \neq j_{2}) \end{cases}$

• The trajectory backbone, \mathcal{B} , as a subgraph of \mathcal{G}

$$\mathcal{N}(\mathcal{B}) = \mathcal{N}(\mathcal{G}) \qquad \qquad \mathcal{E}(\mathcal{B}) = \left\{ (j_1, j_2) \in \mathcal{E}(\mathcal{G}) : \sum_i \mathbbm{1}_{\{\tilde{w}_{ij_1} > 0, \tilde{w}_{ij_2} > 0\}} > 0 \right\}$$

VITAE (Du et. al., BioRXiv, 2023)



• Assume latent variables $Z_i \in \mathbb{R}^d$ satisfy

 $oldsymbol{Z}_i | ilde{oldsymbol{w}}_i \sim \mathcal{N}_d(oldsymbol{U} ilde{oldsymbol{w}}_i, oldsymbol{I}_d)$

A non-linear mapping from the latent space to the high-dimensional observed data

Model f_g by a neural network

- **U**: unknown positions of the vertices in \mathbb{R}^d
- X_i : cell-specific confounding covariates (data source, cell cycle, et. al.)
- We also assume a mixture prior on \widetilde{w}_i

VITAE (Du et. al., BioRXiv, 2023)

- Key contribution: Simultaneous batch effect removal and trajectory analysis
- Loss function:

Reconstruction loss

$$\begin{split} L &= -(1 - \alpha) \sum_{i=1}^{N} \mathbb{E}_{q(\boldsymbol{Z}_{i} | \boldsymbol{Y}_{i}, \boldsymbol{X}_{i})} \log p(\boldsymbol{Y}_{i} | \boldsymbol{Z}_{i}, \boldsymbol{X}_{i}) \\ &+ \beta \sum_{i=1}^{N} D_{\mathrm{KL}}(q(\boldsymbol{Z}_{i} | \boldsymbol{Y}_{i}, \boldsymbol{X}_{i}) \| p(\boldsymbol{Z}_{i})) \\ &- \alpha \sum_{i=1}^{N} \log p(\boldsymbol{Y}_{i} | \boldsymbol{Z}_{i} = \boldsymbol{0}_{d}, \boldsymbol{X}_{i}) \\ &+ \kappa \, \Omega_{\mathrm{MMD}}(\mathcal{D}_{N}) \\ &+ \gamma \, \Omega_{\mathrm{Jacobian}}(\mathcal{D}_{N}). \end{split}$$



- Four penalty terms:
 - *β*-VAE:
 - Set $\beta > 1$ to encourage posteriors of Z_i to lie along trajectory backbone
 - Adjust for confounding X_i and batch effects
 - Soft penalty: help decorrelate **Z**_i from **X**_i
 - MMD loss: used across replicates where the cell populations are known to be the same
 - Jacobian regularizer
 - enhance stability in optimization

$$\Omega_{\text{Jacobian}}(\mathcal{D}_N) = \sum_{i=1}^N \sum_{j=1}^d \sum_{g=1}^G \mathbb{E}_{q(\boldsymbol{Z}_i | \boldsymbol{Y}_i, \boldsymbol{X}_i)} \left[\left(\frac{\partial \boldsymbol{Z}_{ij}}{\partial \boldsymbol{Y}_{ig}} \right)^2 \right]$$

GPfates (Lonnberg et. al., Science Immunology, 2017)

 Model (normalized and dimension-reduced) scRNA-seq data as generated from a mixture of Gaussian processes

$$X = f_c(t) + \varepsilon \quad p(F|T) = \prod_{c=1}^{C} \mathcal{N}(f_c|0, \mathbf{K}_t^c)$$
$$k(t_{n_1}, t_{n_2}) = \sigma_{\text{SE}}^2 \exp\left(-\frac{|t_{n_1} - t_{n_2}|^2}{2l_{\text{SE}}^2}\right)$$

- Infer posterior t | X to estimate each cell's pseudotime
- Prior distribution $p(t_n) = \mathcal{N}(day_n, \sigma_{prior}^2)$
 - Make use of the calendar time
- Use variational Bayes and EM to infer parameters
- For interpretation of each GP component, only allow one branching point



Waddington-OT (Schiebinger et. al., Cell, 2019)

- Make use the cell collection time and assume that cells having a later collection time are descendants of the earlier collected cells
- Estimate transition between cells
 - Optimal transport coupling

$$\pi_{s,t}(\epsilon) = \min_{\pi} \inf_{\pi} \int \int c(x,y)\pi(x,y)dxdy - \epsilon \iint \pi(x,y)\log\pi(x,y)dxdy$$

subject to
$$\int \pi(x,\cdot)dx = \mathbb{Q}_s$$
$$\int \pi(\cdot,y)dy = \mathbb{P}_t.$$

- $\pi(x, y)$: joint distribution at two time points
- c(x, y): pre-defined cost function
- Corresponding optimization problem

$$egin{aligned} \hat{\pi}_{t_i,t_{i+1}} &= rgmin_{\pi} & \sum_{x\in S_i}\sum_{y\in S_{i+1}}c(x,y)\pi(x,y)-\epsilon \iint \pi(x,y)\log\pi(x,y)dxdy \ &+\lambda_1 ext{KL}\left[\sum_{x\in S_i}\pi(x,y)\Big\|d\hat{\mathbb{P}}_{t_{i+1}}(y)
ight]+\lambda_2 ext{KL}\left[\sum_{y\in S_{i+1}}\pi(x,y)\Big\|d\hat{\mathbb{Q}}_{t_i}(x)
ight] \end{aligned}$$



Related papers

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